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Control signal for PID control without derivative gain limitation: The predicted process output is given by. Combining the above equations for a maximum and minimum control signal (and) which corresponds to the points for which the actuator saturates, If the predicted output is in the proportional band, the controller

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Process Dynamics & Control By Dale E. Seborg, Thomas F. Edgar, and Duncan A. Mellichamp PART ONE: INTRODUCTION TO PROCESS CONTROL 1.

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Introduction to Process Control 1.1

Representative Process Control Problems 1.2

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Classification of Process Control

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process liquid and the coolant. Eqs.1 and 2 comprise the dynamic model for the system.

2. Additional assumptions: i. The density ρ and the specific heat C of the process liquid are constant. ii. The temperature of steam T_s is uniform over the entire heat transfer area iii. T_s is a function of P_s , $T_s = f(P_s)$

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